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| 最后学历 | 研究生 | 最后学位 | 工学博士 | 获学位单位 | 华中科技大学 | |
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| 所属学科及学科方向 | 机械工程 | | | 研究方向 1 | 机器人参数辨识与误差补偿 | |
| | 机器人技术 | | | 研究方向 2 | 抓取机构的创新设计 | |
| 工作简历 | <p>[1] 2017.6 至今, 北京信息科技大学, 机电工程学院</p> <p>[2] 2016.7-2017.1, 中国船舶重工集团有限公司第 714 研究所, 舰船技术信息研究部</p> <p>[3] 2011.8-2012.8, 中国航天科技集团有限公司第九研究院, 工艺研究室</p> | | | | | |
| 承担教学任务 | 《机械设计》、《机械设计基础》、《优化设计》、《专业外语》 | | | | | |
| 在研项目情况 | <p>[1] 2019.1.1-2021.12.31: 国家自然科学基金青年基金项目, 基于刚柔耦合模型及多重采样空间的轻量化机械臂标定方法研究, 28.8 万, 主持</p> <p>[2] 2022.1.1-2025.12.31: 国家自然科学基金面上项目, 基于多源误差综合及多重模型协同的蛇形机械臂标定方法研究, 69.6 万, 主持</p> <p>[3] 2021.1.1-2021.9.31: 企业横向项目, BEST 自动生产线技术开发, 155 万, 参与 (第二成员)</p> <p>[4] 2019.1.1-2020.12.31: 北京市教委科研计划一般项目, 15 万, 主持</p> <p>[5] 2018.1.1-2020.12.31: 北京信息科技大学-师资队伍补充计划支持项目, 12 万, 主持</p> | | | | | |
| 主要论著 (近五年) | <p>[1] Zhouxiang Jiang*; Min Huang; Xiaoqi Tang; Yixuan Guo; A new calibration method for joint-dependent geometric errors of industrial robot based on multiple identification spaces, Robotics and Computer-Integrated Manufacturing, 2021. (SCI, 机器人领域 1 区 top)</p> <p>[2] Zhouxiang Jiang*; Min Huang; Xiaoqi Tang; Bao Song; Yixuan Guo; Elasto-geometrical calibration of six-DOF serial robots using multiple identification models, Mechanism and Machine Theory, 2021. (SCI, 机械工程领域 1 区 top)</p> <p>[3] Zhouxiang Jiang*; Min Huang; Xiaoqi Tang; Bao Song; Yixuan Guo; Observability index optimization of robot calibration based on multiple identification spaces, Autonomous Robots, 2020. (SCI, 机器人领域 2 区)</p> <p>[4] Zhouxiang Jiang*; Min Huang; Stable calibrations of six-DOF serial robots by using identification models with equalized singular values, Robotica, 2021. (SCI, 机器人领域 4 区)</p> <p>[5] Zhouxiang Jiang*; Xiaoqi Tang; Optimization of fixture flexibility for irregular geometries of workpiece based on metamorphic mechanisms, The International Journal of Advanced Manufacturing Technology, 2019. (SCI, 制造领域 3 区)</p> <p>[6] Zhouxiang Jiang*; Bao Song; Xiangdong Zhou*; Xiaoqi Tang; Shiqi Zheng; Single setup identification of component errors for rotary axes on five-axis machine tools based on pre-layout of target points and shift of measuring reference, International Journal of Machine Tools & Manufacture, 2015. (SCI, 制造领域 1 区 top)</p> <p>[7] Zhouxiang Jiang*; Bao Song; Xiangdong Zhou*; Xiaoqi Tang; Shiqi Zheng; On-machine measurement of location errors on five-axis machine tools by machining tests and a laser displacement sensor. International Journal of Machine Tools & Manufacture, 2015. (SCI, 制造领域 1 区 top)</p> <p>[8] Zhouxiang Jiang*; Bao Song; Xiangdong Zhou*; Xiaoqi Tang; Shiqi Zheng; Identification of location errors by a touch-trigger probe on five-axis machine tools with a tilting head, International Journal of Advanced Manufacturing Technology, 2015. (SCI, 制造领域 3 区)</p> | | | | | |

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| | <p>[9] Zhouxiang Jiang; Xiangdong Zhou*; Xiaoqi Tang; Shiqi Zheng; Machining tests for identification of location errors on five-axis machine tools with a tilting head. International Journal of Advanced Manufacturing Technology, 2015. (SCI, 制造领域 3 区)</p> <p>[10] Xiangdong Zhou, Zhouxiang Jiang*, Bao Song, Xiaoqi Tang, Shiqi Zheng. A compensation method for the geometric errors of five-axis machine tools based on the topology relation between axes, International Journal of Advanced Manufacturing Technology, 2017. (SCI, 制造领域 3 区)</p> <p>[11] Yixuan Guo; Bao Song; Xiaoqi Tang; Xiangdong Zhou*; Zhouxiang Jiang; A calibration method of non-contact R-test for error measurement of industrial robots, Measurement, 2021. (SCI, 测量领域 2 区)</p> <p>[12] Yixuan Guo; Bao Song; Xiaoqi Tang; Xiangdong Zhou*; Zhouxiang Jiang; A measurement method for calibrating kinematic parameters of industrial robots with point constraint by a laser displacement sensor, Measurement Science and Technology, 2020. (SCI, 测量领域 3 区)</p> <p>[13] Yixuan Guo; Xiaoqi Tang; Xiangdong Zhou*; Bao Song; Zhouxiang Jiang; Yuanlong Xie; Bosheng Ye; Continuous measurements with single setup for position dependent geometric errors of rotary axes on five-axis machine tools by a laser displacement sensor, The International Journal of Advanced Manufacturing Technology, 2018. (SCI, 制造领域 3 区)</p> |
| 主要科研成果 | <p>[1] 基于多重采样空间的机械臂标定方法</p> <p>[2] 单电机驱动下的自适应机械手与夹具</p> <p>[3] 自动化、柔性化生产线</p> |
| 参加学术团体 | |
| 表彰和荣誉 | <p>2020 年度北京信息科技大学青年教师基本功大赛三等奖、最受学生欢迎奖、教学新星称号</p> <p>机电工程学院第六届教学新星优秀奖</p> <p>2018 年度机电工程学院“学术标兵”</p> |
| 备注 | |